- (2) It is possible to prevent overspeeding of the rotor without exceptional piloting skill.
- (d) Emergency high pitch. If the main rotor high pitch stop is set to meet paragraph (b)(1) of this section, and if that stop cannot be exceeded inadvertently, additional pitch may be made available for emergency use.
- (e) Main rotor low speed warning for helicopters. For each single engine helicopter, and each multiengine helicopter that does not have an approved device that automatically increases power on the operating engines when one engine fails, there must be a main rotor low speed warning which meets the following requirements:
- (1) The warning must be furnished to the pilot in all flight conditions, including power-on and power-off flight, when the speed of a main rotor approaches a value that can jeopardize safe flight.
- (2) The warning may be furnished either through the inherent aerodynamic qualities of the helicopter or by a device.
- (3) The warning must be clear and distinct under all conditions, and must be clearly distinguishable from all other warnings. A visual device that requires the attention of the crew within the cockpit is not acceptable by itself.
- (4) If a warning device is used, the device must automatically deactivate and reset when the low-speed condition is corrected. If the device has an audible warning, it must also be equipped with a means for the pilot to manually silence the audible warning before the low-speed condition is corrected.

(Secs. 313(a), 601, 603, 604, and 605 of the Federal Aviation Act of 1958 (49 U.S.C. 1354(a), 1421, 1423, 1424, and 1425); and sec. 6(c) of the Dept. of Transportation Act (49 U.S.C. 1655(c)))

[Doc. No. 5084, 29 FR 16150, Dec. 3, 1964, as amended by Amdt. 29–3, 33 FR 965, Jan. 26, 1968; Amdt. 29–15, 43 FR 2326, Jan. 16, 1978]

PERFORMANCE

§29.45 General.

- (a) The performance prescribed in this subpart must be determined—
 - (1) With normal piloting skill and;

- (2) Without exceptionally favorable conditions.
- (b) Compliance with the performance requirements of this subpart must be shown—
- (1) For still air at sea level with a standard atmosphere and;
- (2) For the approved range of atmospheric variables.
- (c) The available power must correspond to engine power, not exceeding the approved power, less—
 - (1) Installation losses; and
- (2) The power absorbed by the accessories and services at the values for which certification is requested and approved.
- (d) For reciprocating engine-powered rotorcraft, the performance, as affected by engine power, must be based on a relative humidity of 80 percent in a standard atmosphere.
- (e) For turbine engine-powered rotorcraft, the performance, as affected by engine power, must be based on a relative humidity of—
- (1) 80 percent, at and below standard temperature; and
- (2) 34 percent, at and above standard temperature plus 50° F.

Between these two temperatures, the relative humidity must vary linearly.

(f) For turbine-engine-power rotorcraft, a means must be provided to permit the pilot to detemine prior to takeoff that each engine is capable of developing the power necessary to achieve the applicable rotorcraft performance prescribed in this subpart.

(Secs. 313(a), 601, 603, 604, and 605 of the Federal Aviation Act of 1958 (49 U.S.C. 1354(a), 1421, 1423, 1424, and 1425); and sec. 6(c), Dept. of Transportation Act (49 U.S.C. 1655(c)))

[Doc. No. 5084, 29 FR 16150, Dec. 3, 1964, as amended by Amdt. 29–15, 43 FR 2326, Jan. 16, 1978; Amdt. 29–24, 49 FR 44436, Nov. 6, 1984]

§ 29.49 Performance at minimum operating speed.

- (a) For each Category A helicopter, the hovering performance must be determined over the ranges of weight, altitude, and temperature for which takeoff data are scheduled—
- (1) With not more than takeoff power;
- (2) With the landing gear extended; and